NAS-X: Neural Adaptive Smoothing via Twisting

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Summary

Fitting **sequential latent variable models** is hard!

Why? High-variance gradients and discrete latents!

NAS-X = smoothing + reweighted wake sleep

- Low variance and low bias gradients.
- Versatile handles discrete latents.
- Easy to train, minimal computational overhead.
- Significantly outperforms prior methods.

Reweighted Wake Sleep

Fisher's identity: Gradient of log marginal likelihood is a posterior expectation.

 $\nabla_{\theta} \log p_{\theta}(\mathbf{y}_{1:T}) = \mathbb{E}_{p_{\theta}(\mathbf{x}_{1:T}|\mathbf{y}_{1:T})} \left[\nabla_{\theta} \log p_{\theta}(\mathbf{x}_{1:T}, \mathbf{y}_{1:T}) \right]$

RWS estimates expectation via **importance** sampling.

$$\sum_{i=1}^{N} \overline{w}^{(i)} \nabla_{\theta} \log p_{\theta}(\mathbf{x}_{1:T}^{(i)}, \mathbf{y}_{1:T}), \quad \mathbf{x}_{1:T}^{(i)} \sim q_{\phi}(\mathbf{x}_{1:T} \mid \mathbf{y}_{1:T}),$$

$$\overline{w}^{(i)} \propto rac{p_{ heta}(\mathbf{x}_{1:T}^{(i)},\mathbf{y}_{1:T})}{q_{\phi}(\mathbf{x}_{1:T}^{(i)}\mid\mathbf{y}_{1:T})}$$

Estimating Posterior Expectations via Smoothing Sequential Monte Carlo

NAS-X estimates with **smoothing SMC with** twists r. Twists learned via density ratio estimation.

$$\sum_{t=1}^{T} \sum_{i=1}^{N} \overline{w}_{t}^{(i)} \nabla_{\theta} \log p_{\theta}(\mathbf{x}_{t}^{(i)}, \mathbf{y}_{t} \mid \mathbf{x}_{t-1}^{(i)})$$

 $\mathbf{x}_{1:T}^{1:N}, \overline{w}_{1:T}^{1:N} \leftarrow \mathsf{SMC}(\{p_{\theta}(\mathbf{x}_{1:t}, \mathbf{y}_{1:t}), q_{\phi}(\mathbf{x}_{t} \mid \mathbf{x}_{t-1}, \mathbf{y}_{t:T}), r_{\psi}(\mathbf{x}_{t}, \mathbf{y}_{t+1:T})\}_{t=1}^{T})$

Under certain conditions, NAS-X has **unbiased** and **consistent** gradient estimates.

Algorithm

Algorithm 1: NAS-X

Procedure NAS-X(θ_0 , ϕ_0 , ψ_0 , $\mathbf{y}_{1:T}$) $\theta \leftarrow \theta_0, \quad \phi \leftarrow \phi_0, \quad \psi \leftarrow \psi_0$ while not converged do $\mathbf{x}_{1:T}^{1:N}, \overline{w}_{1:T}^{1:N} \leftarrow \mathsf{SMC}(\{p_{\theta}(\mathbf{x}_{1:t}, \mathbf{y}_{1:t}), q_{\phi}(\mathbf{x}_{t} \mid \mathbf{x}_{t-1}, \mathbf{y}_{t:T}), r_{\psi}(\mathbf{x}_{t}, \mathbf{y}_{t+1:T})\}_{t=1}^{T})$ $\Delta heta = \sum_{t=1}^T \sum_{i=1}^N \overline{w}_t^{(i)}
abla_ heta \log p_ heta(\mathbf{x}_t^{(i)}, \mathbf{y}_t \mid \mathbf{x}_{t-1}^{(i)})$ $\Delta \phi = -\sum_{t=1}^T \sum_{i=1}^N \overline{w}_t^{(i)}
abla_\phi \log q_\phi(\mathbf{x}_t^{(i)} \mid \mathbf{x}_{t-1}^{(i)}, \mathbf{y}_{t:T})$ $\theta \leftarrow \texttt{grad-step}(\theta, \Delta \theta)$ $\phi \leftarrow \texttt{grad-step}(\phi, \Delta \phi)$ $\psi \leftarrow \texttt{twist-training}(heta,\psi)$ return θ, ϕ, ψ **Procedure** twist-training(θ , ψ_0) See Algorithm 2 in Appendix 8.3.



References

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